SDSS・すばるHSC銀河団の 弱重カレンズ効果による

可視光観測量と銀河団質量関係の導出

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すばる望遠鏡 Hyper Suprime-Cam (HSC)



More opportunities in these years!

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可視光観測における銀河団

銀河団 "Dark matter halo"



最大の自己重力束縛系 数密度とクラスタリングは **宇宙論**に強く依存。

理論予測 (N体シミュレーション)は 銀河団質量と赤方偏移の関数。

銀河団における銀河進化

More. S et, al.





Observational challenge

I) Mass-richness 関係式

観測を理論モデルをつなげる。



Very important to robustly compare observation with models!

Observational challenge

2) より詳細な系統誤差

-Projection effect: misidentification of haloes as one cluster

-Orientation selection bias: not spherical

Very important to robustly compare observation with models!



SN比を上げるために、銀河団をrichnessビンで (e.g. 20<λ<30) をstackする必要がある。





8,312個の銀河団 (0.1<z<0.33, <u>20<λ<100</u>)

銀河形状と赤方偏移 **3,900**万個の銀河

Richnessビン

Four richness bins for lensing Eight richness bins for abundance

bin index (abundance)	bin index (lensing)	λ_{\min}	λ_{\max}	$\langle \lambda \rangle$	z_{\min}	z _{max}	$\langle z_{\lambda} \rangle$	$\langle p_{\rm cen} \rangle$	$N^{ m raw}_{\lambda_lpha}$	$N^{ m corr}_{\lambda_lpha}$
1 2 3 4 5 6	1 1 2 2 3 3 3	20.0 25.0 30.0 35.0 40.0 47.5	25.0 30.0 35.0 40.0 47.5 55.0	22.3 27.2 32.3 37.4 43.5 51.0	0.10 0.10 0.10 0.10 0.10 0.10	0.33 0.33 0.33 0.33 0.33 0.33	$\begin{array}{c} 0.25 \\ 0.24 \\ 0.24 \\ 0.24 \\ 0.24 \\ 0.24 \\ 0.24 \end{array}$	0.87 0.86 0.86 0.86 0.87 0.88	3133 1762 1146 734 596 381	3488.4 (11.3%) 1790.8 (1.6%) 1164.1 (1.6%) 745.7 (1.6%) 605.2 (1.5%) 386.8 (1.5%)
7 8	4 4	55.0 77.5	77.5 100	63.6 85.8	0.10 0.10	0.33 0.33	0.24 0.23	0.87 0.89	434 126	440.4 (1.5%) 127.8 (1.4%)

 Table 1

 Binning scheme for the redMaPPer clusters and characteristics in each bin

Cluster observables

Weak gravitational lensing





Cluster observables

Weak gravitational lensing

This work

Halo clustering For future cosmological analysis



Mass-richness関係式のモデリング

Two modeling approaches



Mass-richness relation in forward modeling $P(\lambda|M_{ m h})$

Assume
log-normal distribution:

$$P(\ln \lambda | M) d \ln \lambda \equiv \frac{1}{\sqrt{2\pi}\sigma_{\ln \lambda | M}} \exp\left(-\frac{x(\lambda, M)^2}{2\sigma_{\ln \lambda | M}^2}\right) d \ln \lambda$$
where

$$x(\lambda, M) \equiv \ln \lambda - \left[A + B \ln\left(\frac{M}{M_{\text{pivot}}}\right)\right]$$

$$M_{\text{pivot}} = 3 \times 10^{14} M_{\odot} / h$$
Mean relation:

$$\langle \ln \lambda \rangle (M) = \underline{A} + \underline{B} \ln\left(\frac{M}{M_{\text{pivot}}}\right)$$
Scatter relation:

$$\sigma_{\ln \lambda | M} = \underline{\sigma_0} + \underline{q} \ln\left(\frac{M}{M_{\text{pivot}}}\right)$$

In this work, a simple model with **four** free parameters

Model: abundance in richness bin

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$$N_{\lambda_{\alpha}} \equiv \Omega_{\text{tot}} \int_{z_{\min}}^{z_{\max}} dz \, \frac{d^2 V}{dz d\Omega} \int_{M_{\min}}^{M_{\max}} dM \, \frac{dn}{dM} \int_{\ln \lambda_{\alpha, \min}}^{\ln \lambda_{\alpha, \max}} d\ln \lambda \, P(\ln \lambda | M)$$
$$= \Omega_{\text{tot}} \int_{z_{\min}}^{z_{\max}} dz \, \frac{\chi(z)^2}{H(z)} \int_{M_{\min}}^{M_{\max}} dM \, \frac{dn}{dM} \frac{dn}{dM} \frac{S(M | \lambda_{\alpha, \min}, \lambda_{\alpha, \max})}{\sum_{\text{rediction}}^{M_{\max}}}$$

Mass selection function in richness bin

 $\frac{S(M|\lambda_{\alpha,\min},\lambda_{\alpha,\max})}{2} \equiv \int_{\ln\lambda_{\alpha,\min}}^{\ln\lambda_{\alpha,\max}} d\ln\lambda \ P(\ln\lambda|M)$ $= \frac{1}{2} \left[\operatorname{erf}\left(\frac{x(\lambda_{\alpha,\max},M)}{\sqrt{2}\sigma_{\ln\lambda|M}}\right) - \operatorname{erf}\left(\frac{x(\lambda_{\alpha,\min},M)}{\sqrt{2}\sigma_{\ln\lambda|M}}\right) \right]$

Model: lensing in richness bin



In addition to mass-richness relation parameters, we need accurate prediction of mass function and lensing!

Advantages of forward modelingover backward modeling $P(\lambda|M_h)$ $P(M_h|\lambda)$

I) Can use **abundance** measurement -> **stronger constraint**

Backward modeling: cannot use abundance.

Advantages of forward modelingover backward modeling $P(\lambda|M_h)$ $P(M_h|\lambda)$

2) With mass function P(M), can get P(M| λ) from P(λ |M).

Backward modeling: **difficult** to get $P(\lambda|M)$ from $P(M|\lambda)$.

Advantages of forward modelingover backward modeling $P(\lambda|M_h)$ $P(M_h|\lambda)$

3) We **can populate richness** in simulation from $P(\lambda|M)$.

Backward modeling: difficult

Halo emulator for signal

In this work, we fix cosmology to Planck cosmology.

Halo mass function

Lensing profile

We now can calculate model predictions in richness bins with mass-richness parameters.

Full-sky lensing mock catalogs for covariance

We also need *realistic covariance* for MCMC analysis.

$$\chi^{2} = \sum_{i,j} \left[\mathbf{D} - \mathbf{D}^{\text{model}} \right]_{i} \left(\mathbf{C}^{-1} \right)_{ij} \left[\mathbf{D} - \mathbf{D}^{\text{model}} \right]_{j}$$

$$\sum_{\text{Nodel=Forward modeling with emulator}} \left[\mathbf{C}^{-1} \right]_{ij} \left[\mathbf{D} - \mathbf{D}^{\text{model}} \right]_{j}$$

Including:
I) Shape noise (lensing)
2) Poisson noise (abundance)

3) Sample covariance

We used 108 realizations of full-sky lensing maps and halo catalogs in Shirasaki et al. 2017, Takahashi et al. 2017.



Lensing maps from Shirasaki et al. 2015

Realistic setup for covariance estimation of SDSS data, including RA&Dec, redshift, survey boundary and richness distributions.

Covariance estimation results



SDSSの銀河団での解析結果



Reproduce lensing and abundance simultaneously



Reproduce lensing and abundance simultaneously



Complementarity of abundance and lensing









Mass distribution in each richness bins

20<λ<100

30<λ<100



"Projection effect" for 10% contamination?

Identifying more than two haloes along line of sight as **one cluster**. (e.g. Cohn et al. 2007)



We will check this **systematics effect** in simulation box.





We have developed forward modeling method. Joint fitting of abundance and lensing.

Simulation based signal and covariance.

We have applied this for SDSS clusters.

Next steps:

Projection effect test in simulation box
 Add clustering to determine cosmology
 Apply for HSC CAMIRA clusters (z~1)